

GPS based Advanced Vehicle Tracking and Vehicle Control System

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Abstract— Security systems and navigators have always been a necessity of human's life. The developments of advanced electronics have brought revolutionary changes in these fields. In this paper, we will present a vehicle tracking system that employs a GPS module and a GSM modem to find the location of a vehicle and offers a range of control features. To complete the design successfully, a GPS unit, two relays, a GSM Modem and two MCU units are used. There are five features introduced in the project. The aim of this project is to remotely track a vehicle's location, remotely switch ON and OFF the vehicle's ignition system and remotely lock and unlock the doors of the vehicle. An SMS message is sent to the tracking system and the system responds to the users request by performing appropriate actions. Short text messages are assigned to each of these features. A webpage is specifically designed to view the vehicle's location on Google maps. By using relay based control concept introduced in this paper, number of control features such as turning heater on/off, radio on/off etc. can be implemented in the same fashion.

Index Terms— Tracking, GSM, GPS, Vehicle Tracking, Google Map, Google Tracking, Vehicle Control

I. INTRODUCTION

The vehicle tracking system is an electronic device that tracks the vehicle's location. Most of the tracking systems use GPS module to locate the vehicle's position [1]. Many systems also combines communication components such as satellite transmitters to communicate the vehicle's location to a remote user [2]. Google maps are used to view the vehicle's location. The design of the tracking system is divided into three parts; basic design, intermediate design and an advance Design. The basic design of the vehicle tracking system consists of a GSM module, a GPS module, a MCU (ATMEL), a Relay circuit and a LCD. The user sends SMS and the system responds to the user's request by providing the coordinates of a location in accordance to the requirements of mobile phone users through the GPRS network. The intermediate and advance design is an improvement of the basic design. There are five features introduced in the project. SMS codes are specifically assigned to each of these features. For example, if the user sends '555' to the tracking system. The GSM modem will receive the SMS and transmit to the MCU unit, where the SMS code will be compared against the codes stored in the library. In this project, the code '555' is assigned to find the location of a vehicle. So, the MCU will get the location from the GPS module and reply back

to the user with the location coordinates (i.e. Longitude and Latitude). These coordinates can be used to view the location of a vehicle on Google maps. The vehicle tracking system presented in this paper comprises of a cost effective and special tracking technology. It offers an advanced tracking and a variety of control features that facilitate the monitoring and clever control of the vehicle. The tracking systems are not only bounded to shipping industry and fleet tracking but also used in cars as a theft prevention tool.

This paper provides an overview of the background research related to vehicle tracking and control systems, component's choice and full development process of the tracking system. The paper is divided in five main sections: related research, choice of components, design of a system, simulation of designs and implementation process. In the related research section, we will outline the research carried out so far. Then, we will discuss the components used. The design section will focus the software and hardware design process. The assembly of components will be discussed in the implementation section. Finally, the implementation process section will include the software simulations and images of the hardware in working condition.

II. RELATED RESEARCH

Number of papers has been published on the development of vehicle tracking system using GPS and GSM Modem [3],[4],[5],[6],[7],[8],[9],[10],[11],[12],[13] and [14]. In [15], differential GPS algorithm that is capable of providing real-time near PPP service is presented. In [16], error sources in GPS measurement are calculated. In [17], vehicular navigation application is presented. A web application and a mobile application related to vehicle tracking are presented in [18]. In [19] safety challenges related to tracking system and GPS are discussed in great detail. A novel method of vehicle tracking is presented in [20] using wireless sensor technology, passive sensors [21], android based tracking [22], self-power tracking system [23] and tracking system based on cloud computing infrastructure [24]. A vehicle tracking system based on color histogram distance and binary information is implemented [25]. In [26] development of real-time visual tracking system for vehicle safety applications is discussed and the concept of focus of expansion (FOE) is introduced. A low cost real time tracking system that provides accurate localizations

of the tracked vehicle is presented in [27]. Vehicle tracking coupled with vehicle registration number recognition is introduced in [28]. Following huge demand of accurate vehicle tracking systems, researchers proposed number of novel methods [29], [30], [18] to improve the accuracy of tracking systems.

III. CHOICE OF COMPONENTS

A. The Microcontroller unit (MCU)

There are two ways to control an electronic circuit either using: Microprocessor or MCU. The Microprocessors are usually referred to as general-purpose microprocessors because they do not contain RAM, ROM and I/O ports. So, system designers have to add an external RAM, ROM and I/O ports to make a system functional. Addition of these components will make the system bulkier and much more expensive. The advantage of using microprocessor is that the designer can decide the amount of RAM, ROM and I/O ports needed to accomplish a task.

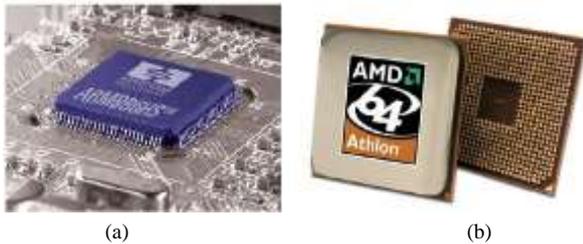


Fig. 1. (a) Microprocessor embedded on a board [31] (b) AMD Microprocessor [32].

However, MCUs have a CPU in addition to the fixed amount of RAM, ROM and I/O ports, which are embedded on a chip with support functions such as a crystal oscillator, timers and serial or analog input output (I/O) [33]. The MCUs are designed for embedded applications and can be used in remote controls, power tools, toys and other appliances. Invention of MCUs has reduced the size and cost of designs. MCUs are suitable where cost and space are critical. There are four types of MCUs (8 bit): 8051 family, PIC, Zilog and Freescale. The MCU families are not compatible with each other, which means, if we write a code for 8051 MCU it will not work on PIC MCU. This is mainly due to different instructions and registers set in each MCU.



Fig. 2. (a) 8051 Family Microcontroller [34], (b) A Microcontroller pin description [35].

To choose among these MCUs, there are specific criteria set for designers: MCU should meet the task at hand efficiently and cost effectively [34]. Software development tools such as compilers, assemblers and debuggers should be available in the market [34]. Wide availability and reliable sources of the MCU used. Designer should also consider the speed, Packaging, power consumption, the amount of RAM, ROM on chip and cost per unit [35].

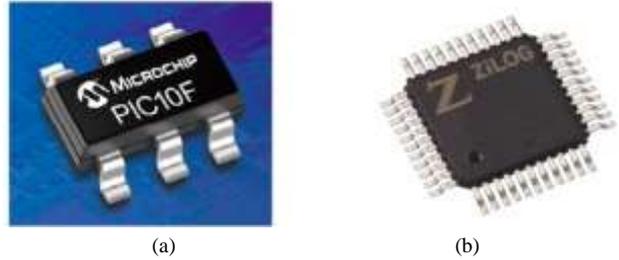


Fig. 3. (a) A PIC Microcontroller [36], (b) A Zilog Microcontroller [37].

B. GSM Modem

A GSM module is a second generation digital mobile cellular technology, which covers a fairly broad geographic area. This offers customized travel, financial, reference and commercial information to the users [38]. It can operate in 400MHz, 900MHz and 1800MHz frequency bands. The GSM modem can accept a SIM card just like a mobile phone and operate on a subscription to a network of mobile data transfer. The GSM Modem supports three types of services namely bearer or data services, supplementary services, and telecommunication services. A typical GSM picture is given below:



Fig. 4. A GSM Modem (Global System for Mobile Communications) [39].

C. GPS Modules

The first GPS (navigation system) was designed by Honda in 1983 [40]. Pioneer claims to be the first with a GPS-based auto navigation system, in 1990 [41]. Magellan claims to have created the first GPS-based vehicle navigation system in the U.S in 1995 [42].

Each GPS (satellite) transmits data that indicates the current time and its location. It transmits signals to a GPS receiver. This receiver requires an unobstructed view of the sky, so they can only be used effectively outdoors. The step by step operation of the GPS can be seen in figure 5.

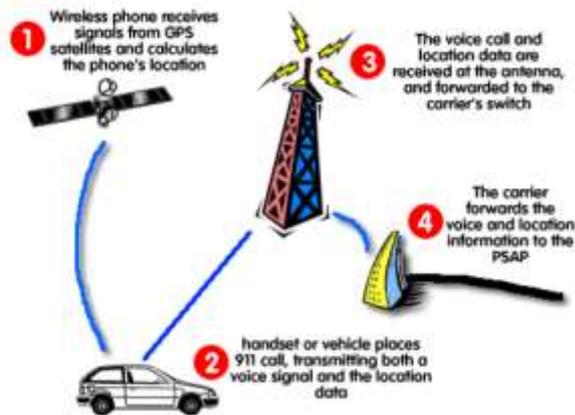


Fig. 5. Various Steps of GPS operations [43].

D. Types of Tracking

There are four types of tracking: direction finding tracking, The LORAN's tracking technique, signpost tracking and GPS based tracking. In direct finding tracking, cellular or PCS wireless systems uses this tracking technique to calculate the bearing from two fixed sites to the mobile. A triangle is created with endpoints at the two fixed points and trigonometry tells the location of a mobile transmitter [44].

Loran tracking technique is used to find the location of an object by using the time difference between receptions

of radio signals from two or higher power fixed transmitters. The system consists of a receiver, and data interface box/modem connected to a separate two-way radio. Based on LORAN signal, the receiver calculates the longitude and latitude in degrees and plotted the location on a map. The LORAN's tracking system has limited resolution, which makes the system impractical. Signpost systems are mostly used in rail lines. A transponder is polled as the train traverses its route. As train pass, it receives handshake from the signpost transmitter. A transmitter on the mobile would report passing the signpost to a system controller [45]. GPS based tracking is used to locate the position of a vehicle. It is a satellite-based navigation system that was developed by the U.S. Department of Defence (DoD) in the early 1970s [46]. Initially, GPS was developed as a military system to fulfil U.S. military needs. However, it was later made available to the civilians, and is now a dual-use system that can be accessed by both military and civilian users.

IV. DESIGN OF A SYSTEM

In order to complete the project successfully, number of steps are followed. A comprehensive review of development process is shown in the "Fig. 6".

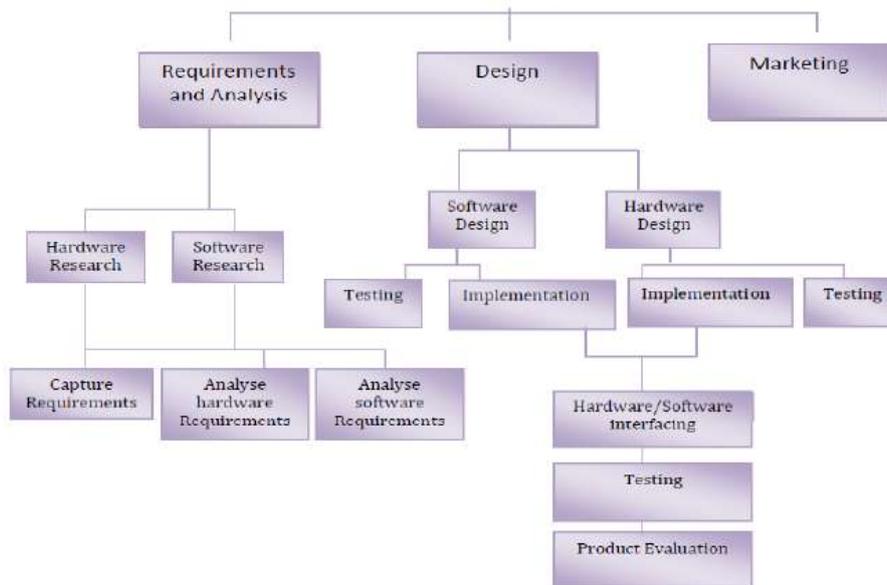


Fig. 6. Development process of our product.

The design is divided into three parts: Basic Design (Original Aim of the project), Intermediate Design (Additional bit) and Advance Design (Additional bit).

There are three ways to operate the vehicle tracking system: Send request via mobile (Basic design), Send request via computer (Intermediate design) and Auto request (Advance design). As shown in the figure 7, there are three ways to send a SMS to the GSM Modem. The basic design will allow the users to send/receive a SMS message using a mobile phone. A SMS can be sent directly from computer using the intermediate design.

The advance design will allow the user to get the locations of a tracking vehicle without entering any command or sending codes to the device. It does the operation automatically. Once the GSM modem receives the user request, it forwards the request to the MCU unit, where it will be processed by comparing the code against already stored codes in the MCU's memory. If the user has sent '111', '222', '333', '444' and '555' code then the device would respond 'Engine kill', 'Engine release', 'Door open', 'Door close' and 'Get location' respectively.



Fig. 7. Operations of a vehicle tracking system.

A. Basic design

Basic design will allow users to send a SMS from a mobile phone to the tracking system and get the response back via SMS. The user will input the longitude and latitude received in a SMS to the designed web page to view the vehicle’s location on Google maps. The basic

design of the vehicle tracking system consists of a GSM module, a GPS module, a MCU (ATMEL), a relay circuit and a LCD. The figure shown below represents the block diagram of the components used in order to build the vehicle tracking system.

First of all, the system will be initialized by sending a SMS to the GSM Modem. The GSM modem will read the SMS and transmit to the MCU unit. The MCU unit will process the request by first checking the mobile number against the stored numbers in its library. If a mobile number matches to the MCU library number, the user request will be further processed by first comparing the request code with the stored codes and then taking the appropriate actions. For example, if the user sends a code ‘555’ to the GSM then the MCU unit will get the coordinates (Longitude and Latitude) from the GPS receiver. However, if the code is ‘111’, ‘222’, ‘333’ and ‘444’, the relay circuit will be operated to lock/unlock the doors and switch ON/OFF the ignition system of the vehicle respectively. Finally, the results will be displayed on the LCD as well as on the computer. The flowchart of basic design is shown in “Fig. 8”.

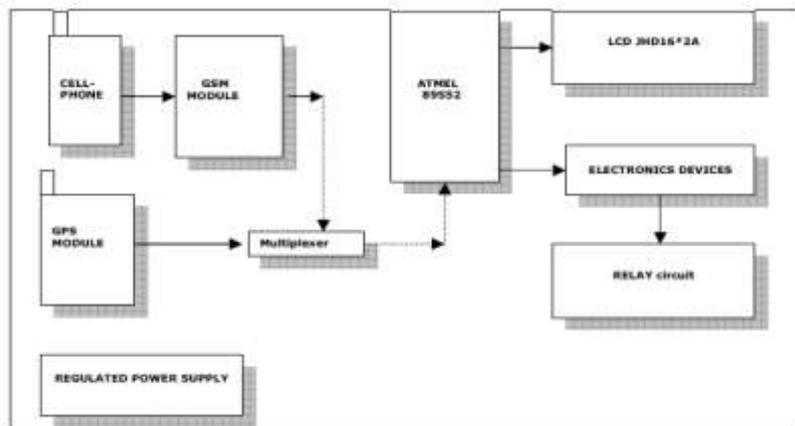


Fig. 8. Block diagram of the project.

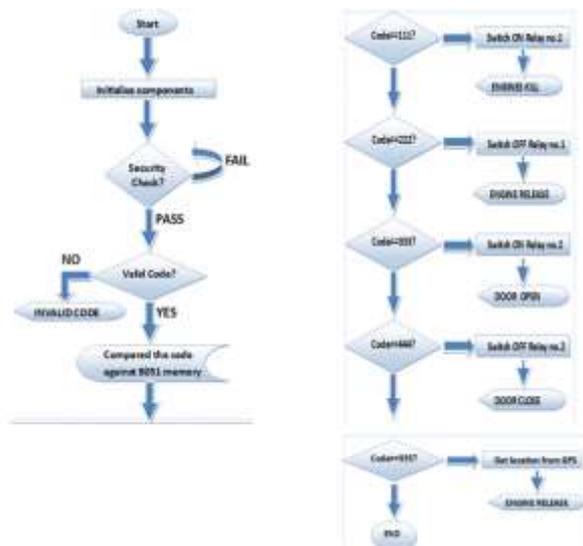


Fig. 9. Flowchart of basic design.

B. Intermediate design

By using the intermediate design, the user can send a SMS from computer directly to the tracking system. The user will copy (rather than typing or inputting) the longitude and latitude to the designed web page to view the vehicle’s location on Google maps. The user can send a SMS to the tracking device either by using SMS gateway software such as i-chat or by connecting the mobile with computer. This connection could be wired or wireless i.e. Bluetooth. Every mobile company provides the software with their mobile which enables users to manage their phones. For example Nokia offers software called Nokia PC Suite. This allows users to establish an interface between Nokia mobile phones and the computer. It can be used to transfer music, photos and other applications. In the vehicle tracking system, we will connect a mobile to the computer using Nokia PC Suite. This will enable user to send/receive SMS to/from the

device. This method of connecting mobile does not require any circuitry hence, reducing the cost and complexity of the project. The only difference between the basic design and the intermediate design is sending method. In the basic design, we have sent a SMS from a mobile phone but the intermediate design allow the users to send a SMS to the device using Nokia PC Suite.

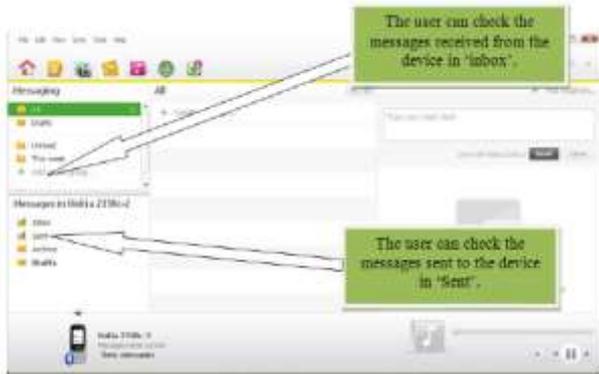


Fig.10. Nokia PC Suite software.

C. Advance design

The advance design will allow the users to track the vehicle's location by just plugging a small device (like USB) to the computer. The system will automatically send the request to the tracking system to get the location and display the received data on Google maps. The advance design of the vehicle tracking system consists of a MAX232, a MCU (ATMEL), a GSM Modem and an IC. The serial port (MAX232 and the RS232) is used to connect the advance design to the computer. The figure shown below represents the block diagram of the components used in order to build the vehicle tracking system. The AT commands are used to make the advance design work. Once the device is plugged to the computer, it will automatically run the system. The computer (via device) will send a SMS to the device and the device will respond in its usual fashion (Respond back via SMS). In the basic and advance designs, the user has to request the location of the device but the advance design offers the plug & play feature.

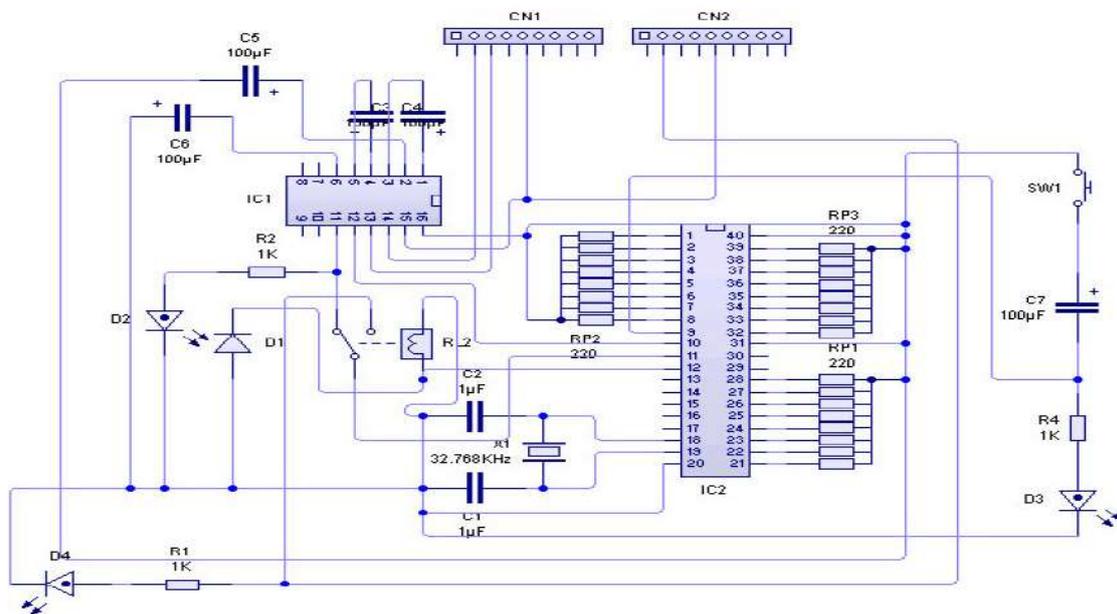


Fig. 11. Circuit diagram of an advance design.

First of all, the advance system will be initialized by setting the mode and the timers. Then, the device (The advance design) will send request to the tracking system (The basic design) automatically. After that the tracking system (The basic design) will perform a security check followed by valid code check. If both condition are true (PASS), then the GPS will operate and the tracking system will respond to the user request by sending a SMS. The device (The advance design) will read the SMS and translate the coordinates.

V. SIMULATION OF DESIGNS

Although there are varieties of software packages, which can be used to simulate the circuit; the most commonly used are the circuit wizard and the PCB

wizard. In order to test circuit, I have used the Proteus design suite (software). The Proteus design suite (software) is used for the electronic circuit simulation, the schematic capture and the printed circuit board (PCB) design. By combining ISIS schematic capture and ARES PCB layout the Proteus design suite (software) provides a powerful, an integrated and easy to use suite of tools for professional PCB design. The Proteus can be used to design a complex circuit for the simulation and the printed circuit board (PCB) layout. Below given figures shows the welcome screen of the Proteus software.

The Proteus software allows the users to simulate the circuit connections and find out the expected results (In real times). I have simulated the Circuit using the Proteus and got the results as shown in "Fig. 13" for the basic design:

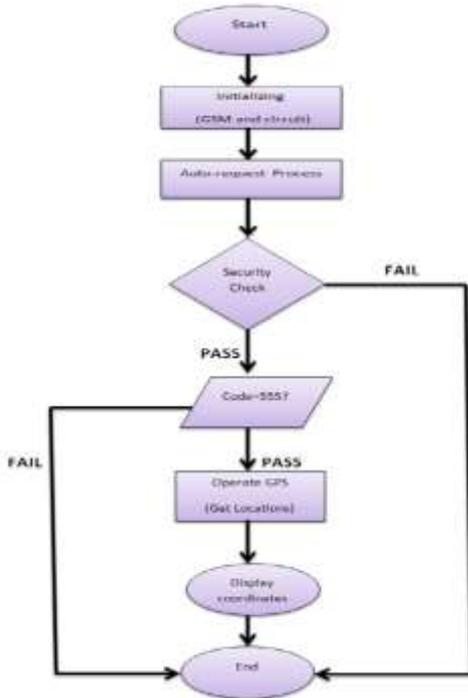


Fig. 12. Flowchart of an advance design.

The advance design was also designed and simulated in the Proteus software. This design will allow the users to locate the vehicle’s location without inputting coordinates in mapping software.

The hardware as shown in “Fig. 14” will be connected to computer straight way using MAX232 to show location without inputting coordinates to Google earth. When we simulate the circuit, the virtual terminal shows the AT commands. These AT commands are used to communicate between the device and the computer. Simulation results from an advance design are shown in figure 13.

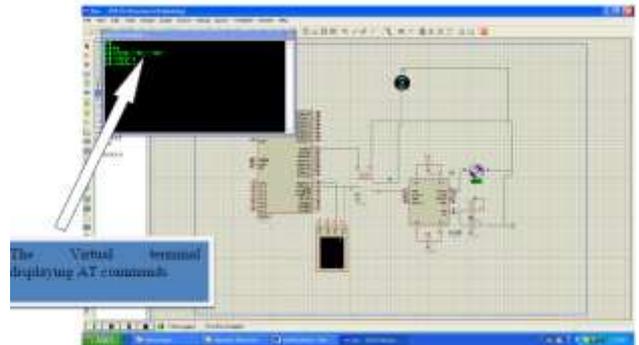


Fig. 15. Execution of AT commands in virtual terminal.

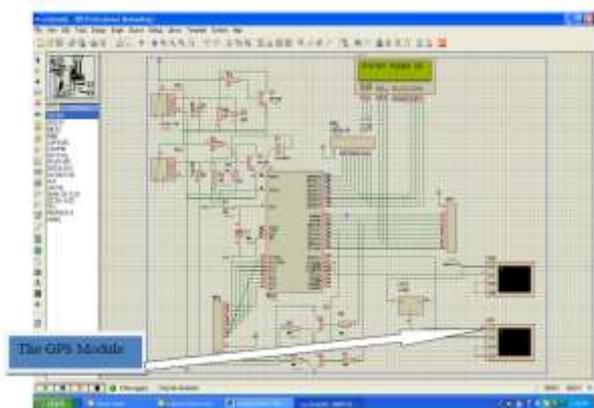


Fig.13. System is powered ‘ON’.

VI. IMPLEMENTATION PROCESS

In the implementation section, we will discuss the steps that were followed to build the vehicle tracking system. Furthermore, this chapter will also focus the reasons behind choosing specific components used in the tracking system. Following steps were taken to build the system: Selecting the right component, choosing the programming language and appropriate software to simulate the design.

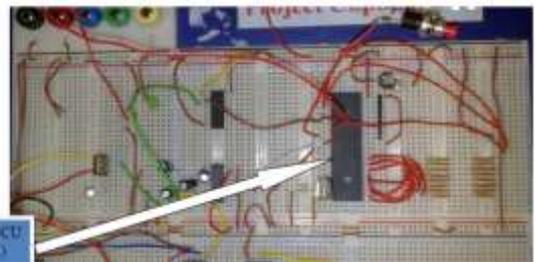


Fig. 16. Prototype of a circuit.

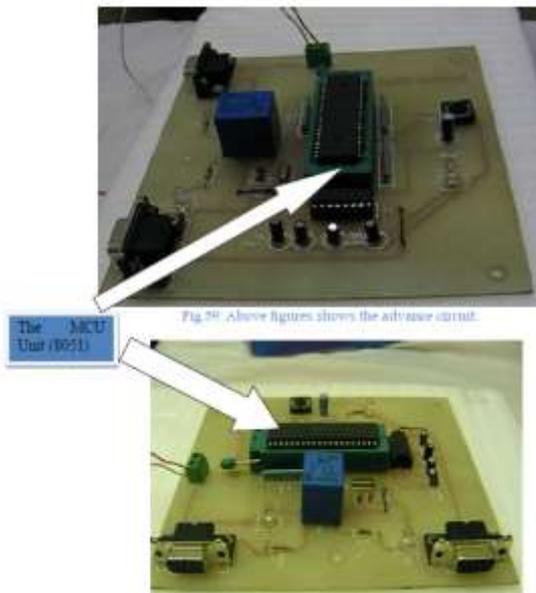


Fig. 14. PCB circuit of an advance design.

A. Selecting the right components

An extensive research has been carried out to find the right components to build the vehicle tracking system. Some of the components used are listed below with a brief description.

The MCU Unit

Each MCU has a unique functionality, which can make them more appropriate for use over the rest. For the basic design and advance design, AT89S52 MCU from 8051 family was used. The AT89S52 is a low-power, high-performance CMOS 8-bit MCU with 8K bytes of in-system programmable flash memory.

In order to free users from the hassle of inputting the longitude (angular distance) and latitude (angular distance), the advance design would require another MCU, which will be connected to computer. This MCU will allow the users to find a precise location directly on the computer without inputting any information. The MCU (AT89S51) has 4 input output ports, which are more than enough to accomplish the tasks of this project. One port will be used for serial communication other will be free for any improvement of the system.

Liquid Crystal Diode (LCD)

Dot Matrix LCD 16*2 (16 char & 2 rows) is used. It can display the location of a vehicle in terms of coordinates and the SMS sent or received by the GSM modem. The two rows of the LCD are used to show the north and east coordinate. The Pin 2 is connected to VCC and pin1 with Ground. Pin no 3 is connected with resistor value of 10K Variable Resistor that is used for the contrast colour of the LCD. Pin no 4 (RS), 5(R/W), 6(EN) are attached with P2.5, P2.6, P2.7 of the MCU respectively. Rests of the 8 pins are attached to port 0 of the MCU.

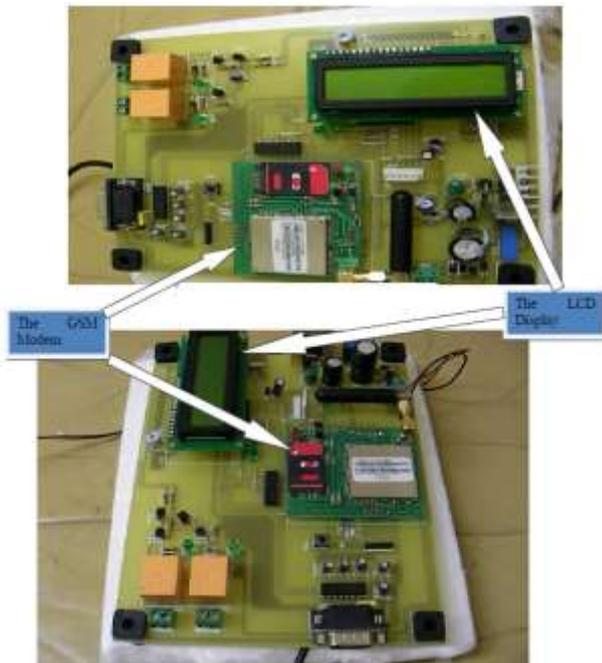


Fig. 17. PCB Board pointing LCD and GSM Modem.

Oscillator

The speed of the MCU depends on the frequency of the oscillator. There are oscillators of different frequencies available. An oscillator of 11.0592 MHz frequency is chosen. Some of the components (i.e. oscillators) used in this project were available in the local lab and simply chosen because of their urgent availability. The MAX232 is used to connect the MCU with RS232, which fits into the serial port of the computer.

The GSM

A GSM modem used in this project is SIMCOM SIM 300DZ. The GSM modem (SIM 300DZ) is tri-band GPRS/GSM device. This can operate over 900, 1800 and

1900 MHz bands. The SIM 300DZ provides RF antenna interface. With the charge circuit integrated inside the GSM module (SIM 300DZ), it is very suitable for the battery power application. With a dimension of 33 x 33 x 3 mm, it can fit in almost all the wireless applications. The SIM card is inserted for the purpose of the user identification in the GSM module.



Fig. 18. Different component of a circuit.

The GPS

One of the most important tasks in the project is designing and implementation of the GPS receiver circuit. I have used M-89 GPS receiver. The receiver has 30 pins. The GPS antenna is used to catch the signals from the satellite. The MCU reads the receiver's data. The GPS outdoor antenna tuned to receive 1575.42 MHz L1 band satellite transmissions. The received signals are passed through a narrow band-pass filter and a pre-amplifier within the antenna. The active antenna circuitry provides 30 dB of gain and requires +5 VDC at 27 milliamps (provided by a Spectra com GPS receiver over the antenna coax). There are 12 pins on the PCB board. First 2 pins (Count from left; top to bottom) and the pins from 7 to 12 are grounded. Pin no 3 is used for LED. The LED blinks, when the GPS receive the data form the satellites. Pin no 4 is use for TX (Transmission) and pin no 6 is connected to +5V.

B. Choosing the right programming language

Although, there are lot of programming languages that could be used to program the MCU, the most common ones are C programming language and Assembly language. The programs written in the assembly language

can execute faster, while programs written in the C programming are easier to develop and maintain. I have used the assembly language in 2nd year and 3rd year of my engineering projects. So, I have better command and knowledge of the assembly language. Therefore; assembly language was chosen to build the vehicle tracking system.

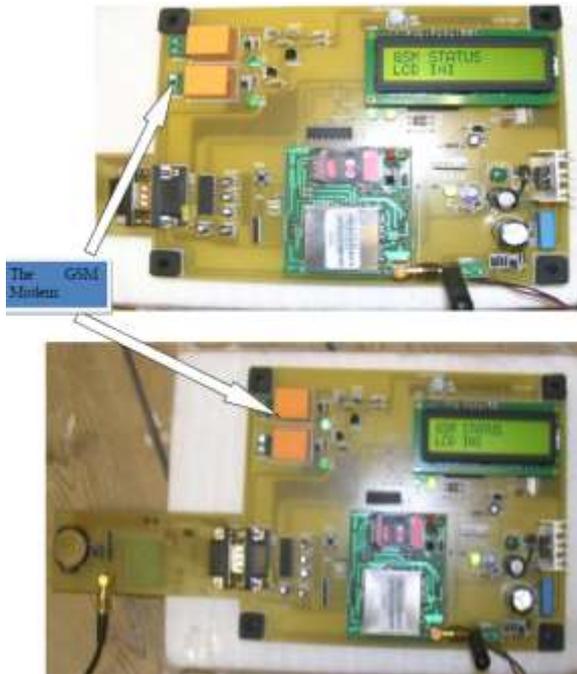


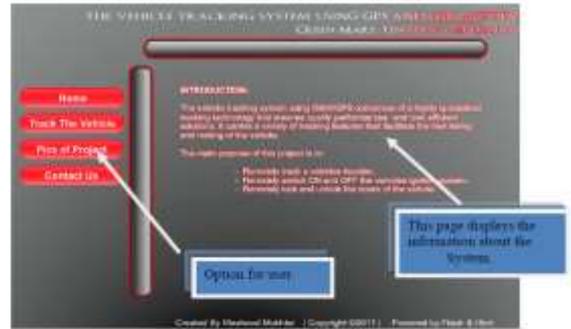
Fig.19. GSM module pointed by arrows.

Web Page to track and control vehicle

HTML language is used to develop the webpage needed to display the location of a vehicle. The Google maps are embedded in my webpage so, that the user can input the longitude and latitude to view the location.



Fig. 20. Webpage of vehicle tracking system.



The below shown page will redirect the user to Google maps. Once the user input or copy the longitude and latitude in the given field and press 'Find Address', the system will show the location on the map.



Fig. 21. Control Panel of the webpage.



Fig. 22. Vehicle located using our tracking system

C. Appropriate software to simulate my design

Although there are varieties of software packages, which can be used to simulate the circuit; the most commonly used are the circuit wizard and the PCB wizard. In order to test the circuit, Proteus design suite (software) is used. It is very powerful tool for the electronic circuit simulation, the schematic capture and the printed circuit board (PCB) design. By combining ISIS schematic capture and ARES PCB layout the Proteus design suite (software) provides an integrated and

easy to use suite of tools for professional PCB design. The Proteus can be used to design a complex circuit for the simulation and the printed circuit board (PCB) layout.

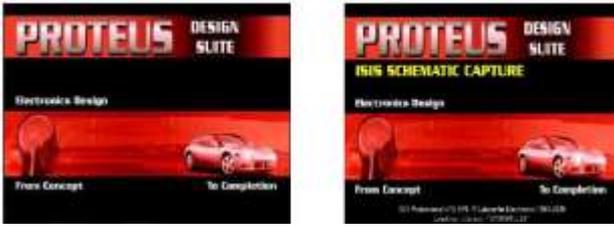


Fig. 23. (a) Proteus Software picture [46], (b) Proteus ISIS Schematic captures [47].

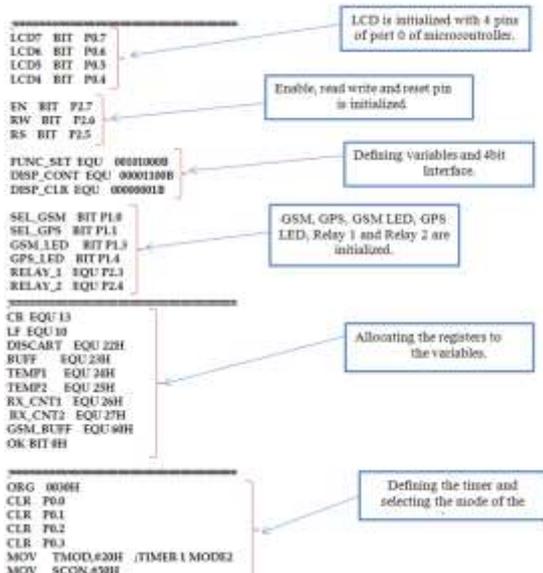
VII. CONCLUSION

The vehicle tracking system presented in this paper can be used for positioning and navigating the vehicle with an accuracy of 10 m. The positioning is done in the form of latitude and longitude along with the exact location of the place, by making use of Google maps. The system tracks the location of a particular vehicle on the user's request and responds to the user via SMS. The received SMS contains longitude and latitude that is used to locate the vehicle on the Google maps. The vehicle tracking system allows a user to: remotely switch ON the vehicle's ignition system, remotely switch OFF the vehicle's ignition system, remotely lock the doors of the vehicle, remotely unlock the doors of the vehicle, and remotely track a vehicle's location. Some changes were made in which most notable change was alteration of the tracking methodology (i.e. Access to 32 channels of satellites instead of 3). The vehicle tracking system was built successfully. However, the vehicle tracking system could be made more robust by using more accurate GPS unit.

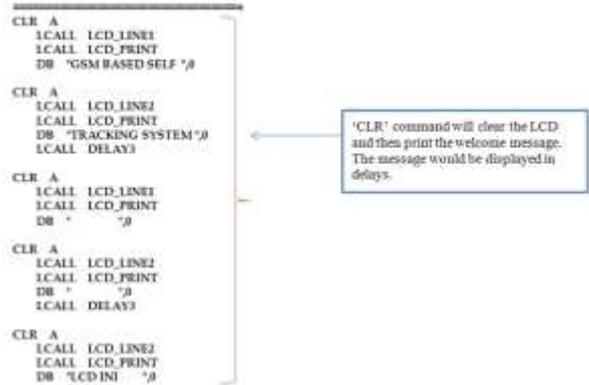
APPENDIX

A. Pseudo Code (Basic Design)

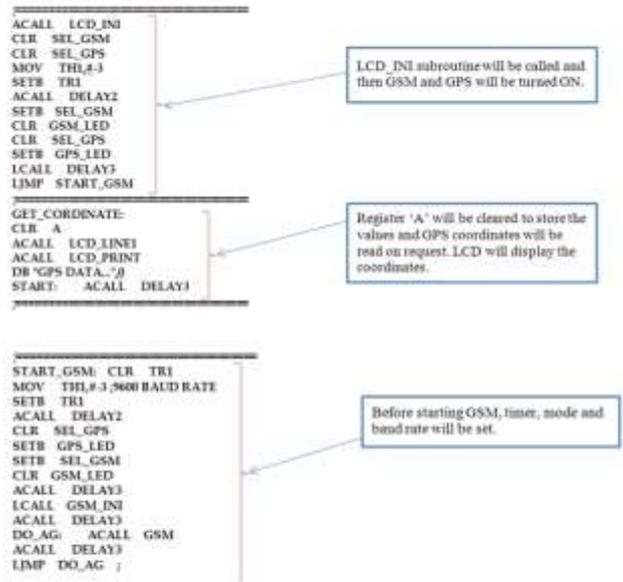
Step 1: First of all, we will initialize the variables and define the timer as shown below:



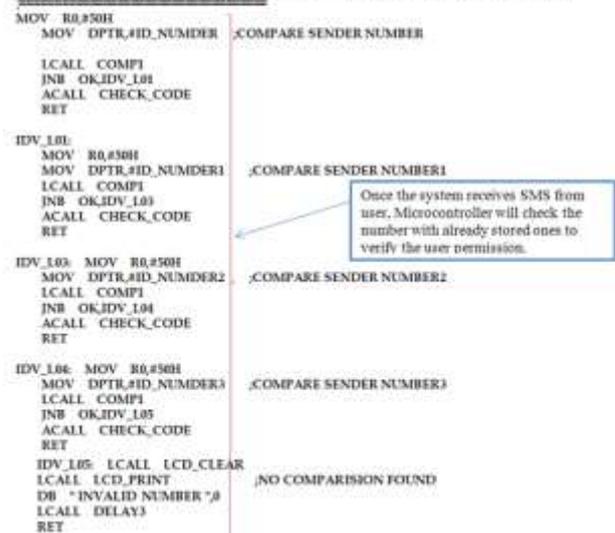
Step 2: we will use the following code to display the welcome message on the LCD:



Step 3: The following code will be used to set the timer of GSM. The GPS and relays will be set and the system will be switched ON:



Step 4: After switching GPS, GSM and relays ON, the system will look for any received messages. If any SMS found, Microcontroller will first verify the user number to confirm that the user has permission to use the system. The following code will be used to verify the user:



Step 5: After verifying the user, System will compare the SMS received with the stores SMS to find out which operation should be performed.

```

CHECK_CODE1: MOV R0,#GSM_BUFF
MOV DPTR,#ENGINE_KILL ;COMPARE SMS WITH ID01
LCALL COMP1
JNB OK_IDV_CODE1
LCALL SMS_ID01
RET

IDV_CODE1: MOV R0,#GSM_BUFF
MOV DPTR,#ENGINE_RLS ;COMPARE SMS WITH ID02
LCALL COMP1
JNB OK_IDV_CODE1
LCALL SMS_ID02
RET

IDV_CODE2: MOV R0,#GSM_BUFF
MOV DPTR,#DOOR_OPEN ;COMPARE SMS WITH ID03
LCALL COMP1
JNB OK_IDV_CODE2
LCALL SMS_ID03
RET

IDV_CODE3: MOV R0,#GSM_BUFF
MOV DPTR,#DOOR_CLOSE ;COMPARE SMS WITH ID04
LCALL COMP1
JNB OK_IDV_CODE3
LCALL SMS_ID04
RET

IDV_CODE4: MOV R0,#GSM_BUFF
MOV DPTR,#GPS_POS ;COMPARE SMS WITH ID05
LCALL GET_COORDINATE
CLR SEL_GPS
SETB GPRS_LED
SETB SEL_GSM
CLR GSM_LED
LCALL GSM_INI
LCALL SMS_ID05
RET

IDV_CODE5: LCALL SMS_ID_NOT_FOUND
RET
    
```

Microcontroller will compare the SMS with store memory to find out which operation is requested by user.

Microcontroller will compare the SMS with store memory to find out which operation is requested by user.

Check if there is any new message received.

```

LCD_CMGL: CLR A
LCALL LCD_LINE1

MOV R,#16
MOV R0,#GSM_BUFF
LOOP: MOV A,R0
LCALL LCD_DATA
INC R0
DJNZ R,LOOP
RET
    
```

Cursor position will be

-----DISPLAY SENDER NUMBER-----

```

LCD_SENDER_NUMBER:
CLR A
LCALL LCD_LINE2
MOV R,#11
MOV R0,#080H
LOOP1: MOV A,R0
LCALL LCD_DATA
INC R0
DJNZ R,LOOP1
RET
    
```

When sender sends a request this subroutine will display the sender's number on the LCD.

```

LCD_SMS: CLR A
LCALL LCD_LINE2

MOV R,#16
MOV R0,#GSM_BUFF
LOOP2: MOV A,R0
LCALL LCD_DATA
INC R0
DJNZ R,LOOP2
RET
    
```

This subroutine will display the received SMS.

```

SMS_ID01: LCALL SMS_INI

LCALL DELAY3
LCALL TX232
DB "ENGINE HAS BEEN KILLED",20,0
CLR RELAY_1
LJMP SMS_EXIT
    
```

"ENGINE HAS BEEN KILLED" will be displayed on the LCD and relay 1 will operate.

```

SMS_ID02: LCALL SMS_INI

LCALL DELAY3
LCALL TX232
DB "ENGINE HAS BEEN RELEASED",20,0
SETB RELAY_1
LJMP SMS_EXIT
    
```

"ENGINE HAS BEEN RELEASED" will be displayed on the LCD and relay 1 will operate.

```

SMS_ID03: LCALL SMS_INI

LCALL DELAY3
LCALL TX232
DB "DOOR HAS BEEN OPENED",20,0
CLR RELAY_2
LJMP SMS_EXIT
    
```

"DOOR HAS BEEN OPENED" Message will be displayed on the LCD and relay 2 will operate.

```

SMS_ID04: LCALL SMS_INI

LCALL DELAY3
LCALL TX232
DB "DOOR HAS BEEN LOCKED",20,0
SETB RELAY_2
LJMP SMS_EXIT
    
```

"DOOR HAS BEEN LOCKED" Message will be displayed on the LCD and relay 2 will operate.

```

UNAUTHORIZED_NUM:
ACALL SMS_INI
LCALL DELAY3
LCALL TX232
DB "ACCESS DENIED",20,0
LJMP SMS_EXIT
    
```

"ACCESS DENIED" Message will be displayed on the LCD (in-case unauthorized entry detected).

```

SMS_ID_NOT_FOUND:
ACALL SMS_INI
LCALL DELAY3
LCALL TX232
DB "INVALID CODE: PLEASE ENTER THE CORRECT CODE",20,0
LJMP SMS_EXIT
    
```

"INVALID CODE" Message will be displayed on the LCD (in-case wrong code is entered).

```

SMS_INI: LCALL LCD_CLEAR
LCALL LCD_PRINT
DB "SENDING SMS",0
LCALL DELAY3
LCALL TX232
DB "AT+CMGF=1",CR,LF,0
LCALL DELAY3
LCALL TX232
DB "AT+CMGS=",0,0
MOV R,#11
MOV R0,#080H
    
```

Before responding to user, the message "SENDING SMS" will appear. This is done by first clearing the LCD and then reading the values of SMS.

```

SMS_L1: MOV A,R0
LCALL TX
INC R0
DJNZ R,SMS_L1
MOV A,#34
LCALL TX
MOV A,#CR
LCALL TX
LCALL DELAY3
RET
    
```

After responding to user, the message "SENT" will appear on LCD. This is done by first clearing the LCD and then printing the values of SMS.

```

SMS_EXIT: MOV R,#2
LLOOP: ACALL BX
DJNZ R,LLOOP
ACALL DELAY3
ACALL DELAY3
ACALL DELAY3
ACALL TX232
DB "AT+CMGF=0",CR,LF,0
ACALL DELAY3
LCALL LCD_CLEAR
LCALL LCD_PRINT
    
```

```

DB "SENT",0
RET
    
```

```

LCD_LINE1: ADD A,#080H
SJMP LCD_COM

LCD_LINE2: ADD A,#0C0H
SJMP LCD_COM
    
```

Cursor position will be

Step 6: Different codes are assigned for different operation. System will perform the operation and display the operation on the LCD.

```

CMGL: DB "+CMGL",0
ENGINE_KILL: DB "111",0
ENGINE_RLS: DB "222",0
DOOR_OPEN: DB "333",0
DOOR_CLOSE: DB "444",0
GPS_POS: DB "555",0
    
```

Different codes are assigned to different operation.

```

ID_NUMBER: DB "+44793",0,4484,0
ID_NUMBER1: DB "+44794",0,3035,0
ID_NUMBER2: DB "+44757",0,7261,0
ID_NUMBER3: DB "+44756",0,8410,0
    
```

Mobile numbers are assigned to communicate.

END

B. Pseudo Code (Advance Design)

Step1: First of all, we will initialize the variables and AT commands used in the code. Then the timer and mode will be set to enable reception of serial data.

```

#include <reg51.h>
void delay(unsigned int x);
sbit P2=P2^2;
void send_ACK();
void send_GSM(unsigned char arr[],unsigned int length,bit c);
void send_GSMa(unsigned char arr[],unsigned int length);
unsigned char chr;
    
```

Initializing the variables

```

unsigned char code at[]="AT";
unsigned char code atc[]="ATE";
unsigned char code cmgl[]="AT+CMGF=1";
unsigned char code cmgs[]="AT+CMGS=\"0044793276484\"";
unsigned char code cmgsa[]="AT+CMGS=\"0044757261\"";
unsigned char code cmgsb[]="AT+CMGS=\"00447568410\"";
unsigned char code cmgs3[]="AT+CMGF=1";
unsigned char code cmgs4[]="AT+CMGF=1";
unsigned char code cmgs5[]="555";
    
```

AT commands are used to control GSM modem and send auto request.

```

unsigned char dat[30];
unsigned int i,j,k;
void main()
{
P2=0;
TMOD=0x20;
TH1=0x00;
SCON=0x30;
TR1=1;
delay(100);
}
    
```

The timer and mode will be set up by enabling reception of serial data.

Step2: Now, The AT command will be sent to the GSM Modem with delays.

```

while(1)
{
j=0;
i=0;
k=0;
r=1;

delay(500);
send_GSM(&at,2,0);
delay(100);
send_GSM(&ate,4,0);
delay(100);
send_GSM(&+psms,17,0);
delay(100);
send_GSM(&+cmgf,9,0);
delay(100);
send_GSM(&+cmgsa,24,0);
delay(100);
send_GSM(&+ms=,3,1);
delay(500);
send_GSM(&+cmgs,9,0);
}

void send_GSM(unsigned char arr[],unsigned int length,bit c)
{
  unsigned int i;
  for(i=0;i<length;i++)
  {
    SBUF=arr[i];
    while(TI==0);
    TI=0;

    if(c==0)
    {
      delay(1);
      SBUF=0x0A; //code for line feed.
    }

    while(TI==0);
    TI=0;
    SBUF=0x0D; //code for carriage return.
    while(TI==0);
    TI=0;

    else if(c==1)
    {
      delay(10);
      SBUF=0x1A; //code for ctrl+z
      while(TI==0);
      TI=0;
    }
  }
}

```

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